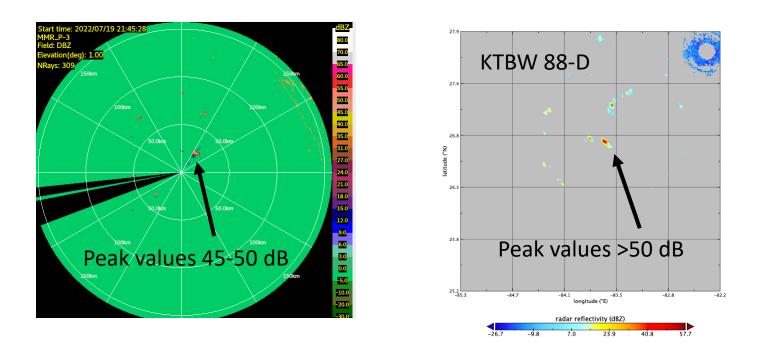
> MMR Test Flight (20220719I1) [Reasor et al.]

- Jan 2021 (revised Feb 2022) HRD/NSSL stated requirements for MMR CfRadials
- 2022071911 was first opportunity to see if suitable CfRadial changes were made
 - Conclusion: Most important request not implemented properly X

```
first filter:units = "meters" ;
              first filter: FillValue = -9999.f ;
       float stc params ;
                                                                               CfRadial 1.3 requires scale factor and add offset
              stc params:long name = "stc params" ;
              stc params:units = "Db" ;
                                                                               attributes if values stored in byte format:
              stc params: FillValue = -9999.f ;
      float radar beam width h ;
              radar beam width h:long name = "half power radar beam width h channel"
              radar beam width h:units = "degrees" ;
                                                                               Float DBZ = (byte DBZ value) * scale factor + add offset
              radar beam width h: FillValue = -9999.f ;
              radar beam width h:meta group = "radar parameters" ;
       float radar beam width v :
              radar beam width v:long name = "DBZ" ;
                                                                            1) Scale factor, add offset attributes added to wrong variable
              radar beam width v:units = "dB " ;
              radar_beam_width_v:_FillValue = -9999.f ;
                                                                            2) Scale factor, add offset should be attributes of DBZ
              radar beam width v:meta group = "radar parameters"
              radar beam width v:sampling ratio = 1.f ;
                                                                            3) Scale factor value shown seems incorrect (see next slide)
              radar beam width v:add offset _ 0.1 ;
              radar beam width v:scale factor = 0.375f
              radar beam width v:coordinate = "time range" ;
              radar beam width v:grid mapping = "grid mapping" ;
       float VEL(time, range) ;
              VEL:long name = "VEL";
                                                         Because MMR processing doesn't appear to flag low SNR
              VEL: FillValue = -9999.f ;
             VEL:units = "meters per second" ;
                                                         regions (as other research radars do), instead reporting a min
      byte DBZ(time, range) ;
              DBZ:long name = "DBZ" ;
                                                         value of 0 dB for weak (<0 dB) echo and noise (<<0 dB), we
              DBZ: FillValue = -9999.f ;
             DBZ:units = "dB" ;
              DBZ:coordinate = "time range" ;
                                                         requested:
              DBZ:grid mapping = "grid mapping";
// global attributes:
                                                       DBZ:comment = "Reflectivity less than 0 dB has been assigned a value of 0 dB"
              :Conventions = "CF-1.3" ;
              :title = "MMR CFRadial Scientific Data"
              :institution = "Harris-EDO and IAI-ELTA" ;
              :references = "Conversion software netCDF 4.4.0" ;
              :source = "APY-11 ELM2022 Radar" ;
              :history = "" ;
              :comment = "netCDF libraries Version 4.4.0";
              :instrument name = "MMR P-3" ;
```

MMR Test Flight (2022071911)

Use HawkEye to visualize the HWX byte DBZ data



Conclusions, questions and recommendations:

- 1) The byte DBZ values seem to correspond well to the 88-D values
- 2) Is scale_factor = 1.0 and add_offset = 0.0 for DBZ?
- 3) If "yes" to 2), then move those attributes to DBZ and assign the proper values

MMR Test Flight (2022071911)

– Were other requests implemented properly?

```
float radar_beam_width_h;
    radar_beam_width_h:long_name = "half_power_radar_beam_width_h.channel";
    radar_beam_width_h:units = "degrees";
    radar_beam_width_h: FillValue = -9999.f;
    radar_beam_width_w:
    radar_beam_width_v:long_name = "DBZ";
    radar_beam_width_v:pilong_name = "DBZ";
    radar_beam_width_v:FillValue = -9999.f;
    radar_beam_width_v:mits = "dB ";
    radar_beam_width_v:sampling_ratio = 1.f;
    radar_beam_width_v:sampling_ratio = 1.f;
    radar_beam_width_v:scale_factor = 0.375f;
    radar_beam_width_v:coordinate = "time_range";
    radar_beam_width_v:glid_mapping = "grid_mapping";
```

Requested: horizontal/vertical beam width variables with proper values

- radar_beam_width_v = 5.6
- radar_beam_width_h = 1.4

Note: The attributes of radar_beam_width_v should mirror those of radar_beam_width_h X

Requested: standard variable names DBZ and VEL \checkmark

Note: NAW reflectivity variable is now also called DBZ (but it has 4 values within 1-deg azimuth, then a .5-deg jump)

Requested: Nyquist velocity variable contain proper value

• nyquist_velocity = 6.8703645

Requested: beam azimuth and elevation clarified as aircraft-relative or earth-relative ✓

Requested: clarification on why _FillValue = -9999.f if that value is never used! X

```
float rotation(time) ;
        rotation:long name = "ray rotation angle relative to platform" ;
        rotation:units = "degrees" ;
        rotation: FillValue = -9999.f ;
float tilt(time) ;
        tilt:long name = "ray tilt angle relative to platform" ;
        tilt:units = "degrees" ;
        tilt: FillValue = -9999.f ;
float azimuth(time) ;
        azimuth:standard name = "ray azimuth angle" ;
        azimuth:long name = "azimuth angle from true north" ;
        azimuth:units = "degrees" ;
        azimuth:axis = "radial azimuth coordinate" ;
        azimuth: FillValue = -9999.f ;
float elevation(time) ;
        elevation:standard_name = "ray_elevation_angle" ;
        elevation:long name = "elevation angle from horizontal plane" ;
        elevation:units = "degrees" ;
        elevation:axis = "radial elevation coordinate" ;
        elevation: FillValue = -9999.f ;
```

MMR Test Flight (2022071911)

– Were other requests implemented properly?

Requested: variables northward_wind, etc. be populated with correct values from the INU

- northward_wind, eastward_wind, vertical_wind empty X
- heading_rate, pitch_rate, roll_rate populated (need to verify values) ?

Requested: proper range and range to center of first gate information ?

range = 40.47, 160.38, 280.29, 400.2, 520.11, 640.02, 759.93, 879.84, 999.75, 1119.66, 1239.57, 1359.48, 1479.39, 1599.3, 1719.21, 1839.12, 1959.03, 2078.94, 2198.85, 2318.76, 2438.67, 2558.58, 2678.49, 2798.4,

HWX

Try: Compare distance to cell in image with reported range

float range(range) ;
 range:standard_name = "projection_range_coordinate" ;
 range:long_name = "Range_from_instrument_to_center_of_gate" ;
 range:units = "meters" ;
 range:spacing_is_constant = "true" ;
 range:axis = "radial_range_coordinate" ;
 range:meters_to_center_of_first_gate = -29 ;
 range:meters_between_gates = 149 ;
 range:num of range cells = 1296 ;

range = -29.5, 120.39, 270.28, 420.17, 570.06, 719.95, 869.84, 1019.73, 1169.62, 1319.51, 1469.4, 1619.29, 1769.18, 1919.07, 2068.96, 2218.85, 2368.74, 2518.63, 2668.52, 2818.41, 2968.3, 3118.19, 3268.08, 3417.97,

NAW

Requested: similar attribute changes for DBZ in NAW files 🗸 / X

byte DBZ(time, range) ;
 DBZ: FillValue = -9999.f ;
 DBZ:sampling_ratio = 1.f ;
 DBZ:units = "dB " ;
 DBZ:long_name = "DBZ" ;
 DBZ:add_offset = 0.f ;
 DBZ:scale_factor = 0.375f ;
 DBZ:cordinate = "time range" ;
 DBZ:grid_mapping = "grid_mapping" ;
}

scale_factor probably should be 1.0 no comment clarifying meaning of DBZ=0 X Final FYI: Something is wrong with VEL! Values are mostly 0 with **pos. integer** values [1,2,3,4,5,6] up to the Nyquist velocity.